



SHM Technologies for Wind Turbine Blades

- **EOLIAN Webinar: A new generation of sustainable wind turbine blades**
- 11th December 2025, 10:00-11:30 CET

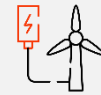
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This project has received funding from the European Union's Horizon Europe research and innovation programme under grant agreement no. 101147532.

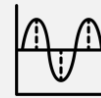




CONTENTS



Smart Health Monitoring Technologies



Ice and Erosion Detection Systems



Eolian Project Approach



Electrochemical impedance spectroscopy:
Impedance Results



Conclusions and future phases

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Funded by
the European Union

1. SHM Technologies for Wind Turbine Blades

- **Structural Health Monitoring (SHM)** in wind turbine blades is essential to maintain efficiency, safety, and reduce maintenance costs

LEADING EDGE

- High particle/rain/hail impact and ice accretion / adhesion
- $v_r \uparrow \uparrow$ Energy impact
- Aerodynamic degradation and structural damage

Physical mechanisms

- LEE:** Repeated impacts remove material
- LEI:** Accretion of supercooled droplets (Atmospheric Icing → Rime and Glaze)

Key Impacts

Leading Edge Erosion (LEE)

- AEP loss 1–6 %
- Pitch control: Drag $\uparrow$ Lift $\downarrow$
- Structural lifetime $\downarrow$

Leading Edge Icing (LEI)

- Power loss 20–50 %
- Unbalanced mass / vibrations
- Risks: ice throw / shutdown



SHM

DETECT

ACTUATION

OPTIMISATION

Sensors: strain, acoustic emission, vibration, thermal sensors, cameras, UAVs.
Processing: filtering, time–frequency transforms, physics-based models.
ML/AI: CNN/YOLO for images, TCN/LSTM for SCADA, autoencoders.
Decision: damage detection, severity classification, prognosis.

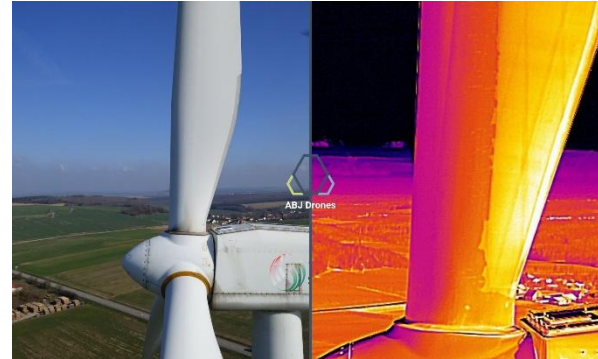
2. Erosion Detection Technologies - Classification

Technology	Detects	Advantages	Limitations	Maturity
Visual / Drone inspection	Surface erosion, pits, cracks, coating loss	Direct observation, well-established, high accuracy	Requires turbine shutdown or access; periodic only, not continuous	High
Image-based ML (drone or ground photos)	Surface damage patterns, severity classification	Scalable, automated assessment, good for fleet-level monitoring	Dependent on image quality; misses subsurface damage; needs labelled data	Medium
Far-field aeroacoustics (microphone arrays)	Noise changes caused by roughness or erosion	Non-contact, remote, no blade modification	Sensitivity reduced in turbulent farms; validated mainly in wind-tunnel	Medium
CFD + aeroacoustics simulation (predictive)	Expected erosion progression & acoustic signature	Useful for prediction, design, coating testing	Not real-time; depends on accurate environmental inputs	Medium
SCADA + Performance/Power Curve deviation	Aerodynamic degradation from roughness/erosion	No added hardware; scalable to entire fleet	Indirect, cannot locate damage; confounds with other losses	Low-Medium
Structural vibration response	Changes in dynamic response due to mass/shape loss	Uses existing sensors in some turbines; potential early indication	Erosion produces subtle changes → low sensitivity; noise masking	Low
Rain / impact erosion modelling (material & physics-based)	Predicted coating wear due to rain/particles	Supports maintenance planning + risk maps	Predictive only; requires validation; site-specific	Medium
Coating/erosion sensors (embedded or surface)	Coating degradation or thickness loss	Direct, continuous monitoring possible	Prototypes only; integration in blades complex; durability issues	Low

2. Erosion Detection Technologies – Examples



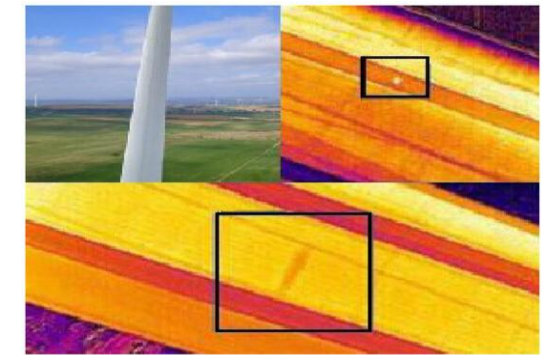
Visual RGB Inspection



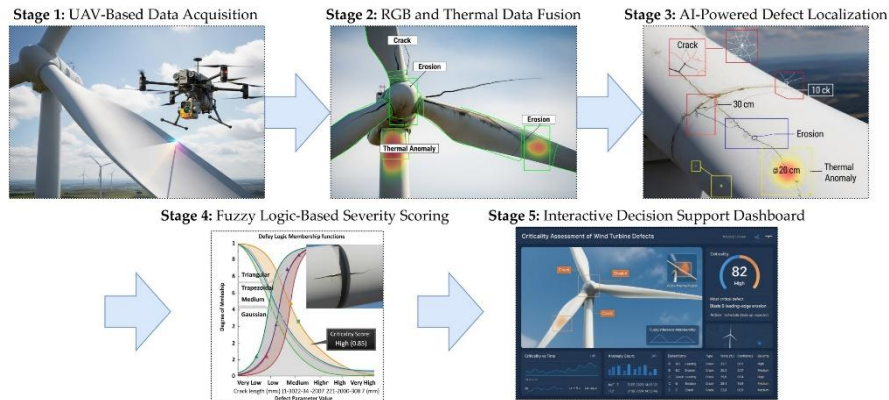
Visual IR Inspection



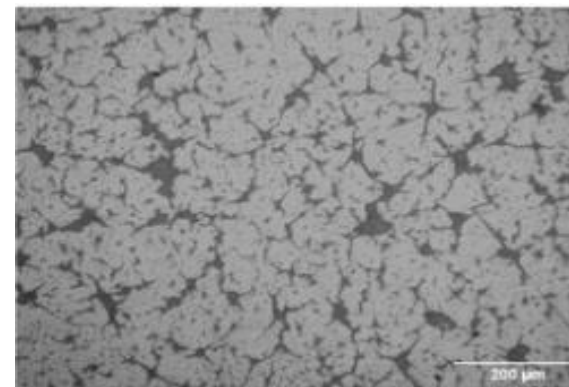
Acoustic emission sensor installed on a turbine blade



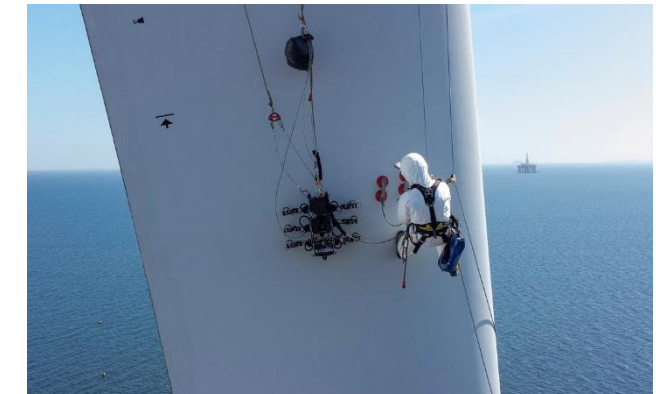
LiDAR-based drone inspection and modeling



Multi-sensor integration



Microscopy Inspection



Robotic crawler inspection

2. Ice Detection Technologies - Classification

Technology	Detects	Advantages	Limitations	Maturity
SCADA + ML	Ice via operational changes	No extra hardware, scalable	Only detects when turbine operates, may confuse with faults	High
Rotor vibration	Blade mass changes	Sensitive, can retrofit, works during operation	Only estimates ice amount, not location	Medium-high
Vibration + ML	Early ice accumulation	Can distinguish subtle ice, early warning	Needs good training data, possible false alarms	Medium
On-blade sensors (capacitive/impedance)	Ice on blade surface	Direct detection, independent of operation	Hardware installation, maintenance, cost	Medium
Acoustic emission	Ice-induced stress/acoustic signals	Early detection, non-intrusive	Sensitive to noise, complex installation	Low-medium
Cameras (RGB/Thermal)	Visual/thermal ice	Direct detection	Weather/visibility limitations	Medium
FBG / temperature sensors	Load/temperature changes	Embedded, continuous monitoring	Expensive, complex installation	Medium
Aeroacoustics	Ice-induced noise	Potentially early detection	Requires modeling, experimental	Low-medium

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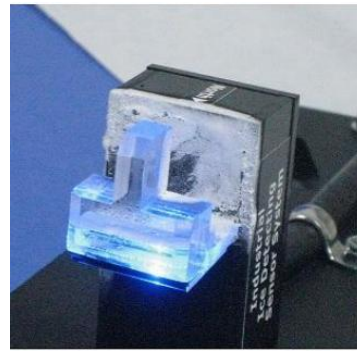
2. Ice Detection Technologies – Examples



Ultrasonic vibrating finger



Vertical rotating cylindric load cell



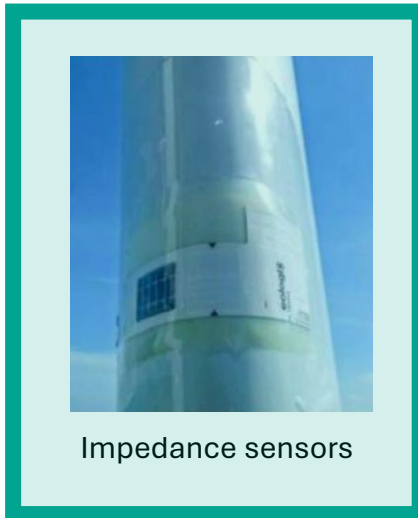
Change of opacity and reflection detector



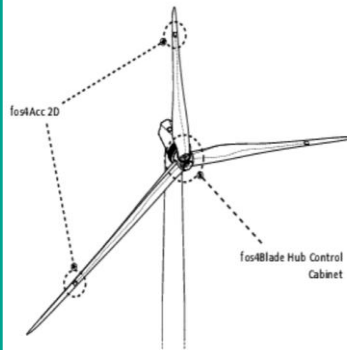
IR camera to for IR reflection change



Impedance/resistive probe



Impedance sensors



Fiber optic sensors



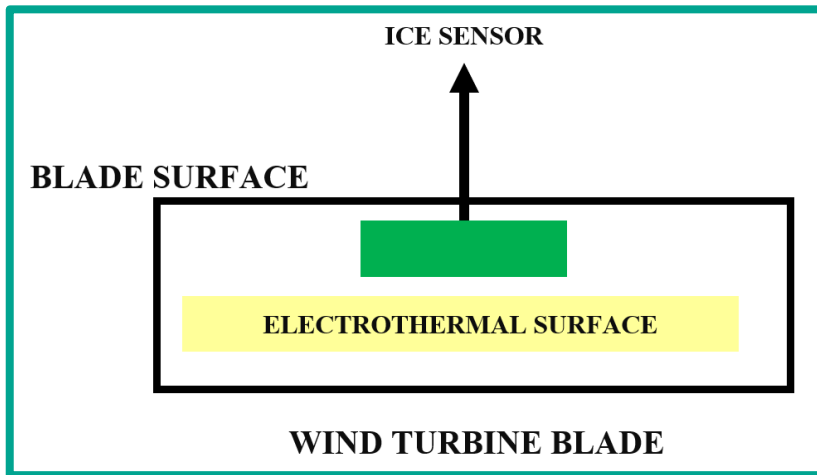
Piezo electric sensors



Structural acoustic sensors

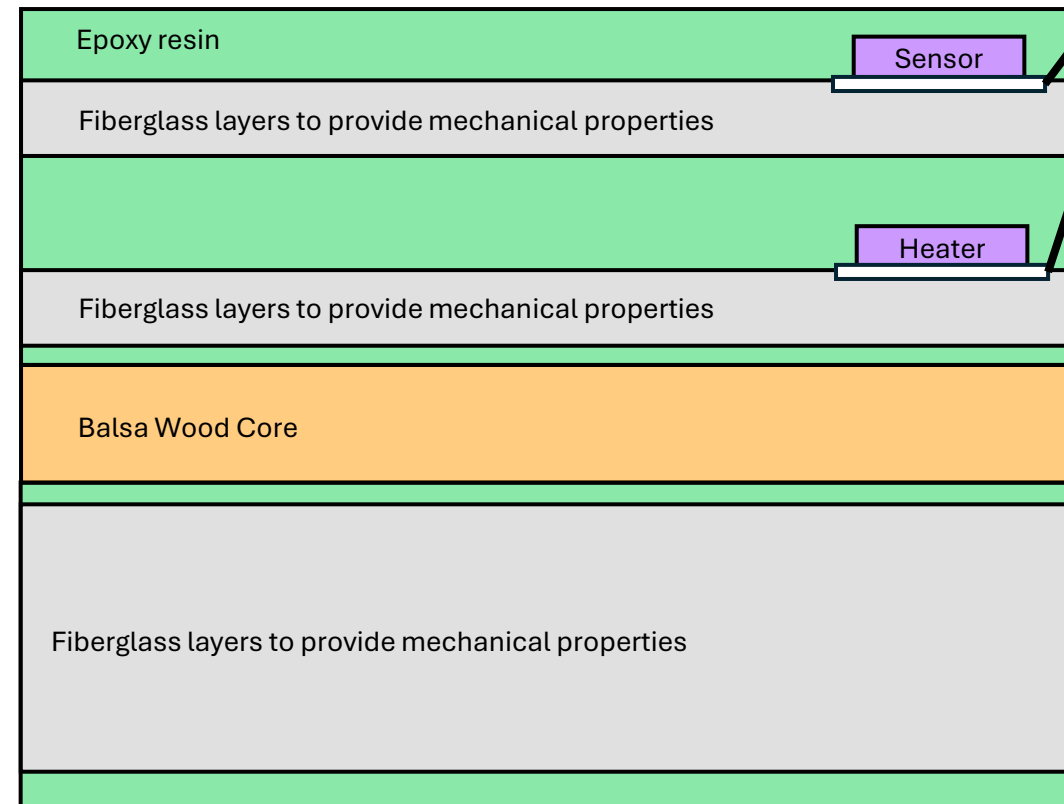
3. EOLIAN PROJECT APPROACH

CONCEPT



DEMONSTRATORS DESIGN (Cross section)

Wind Blade surface



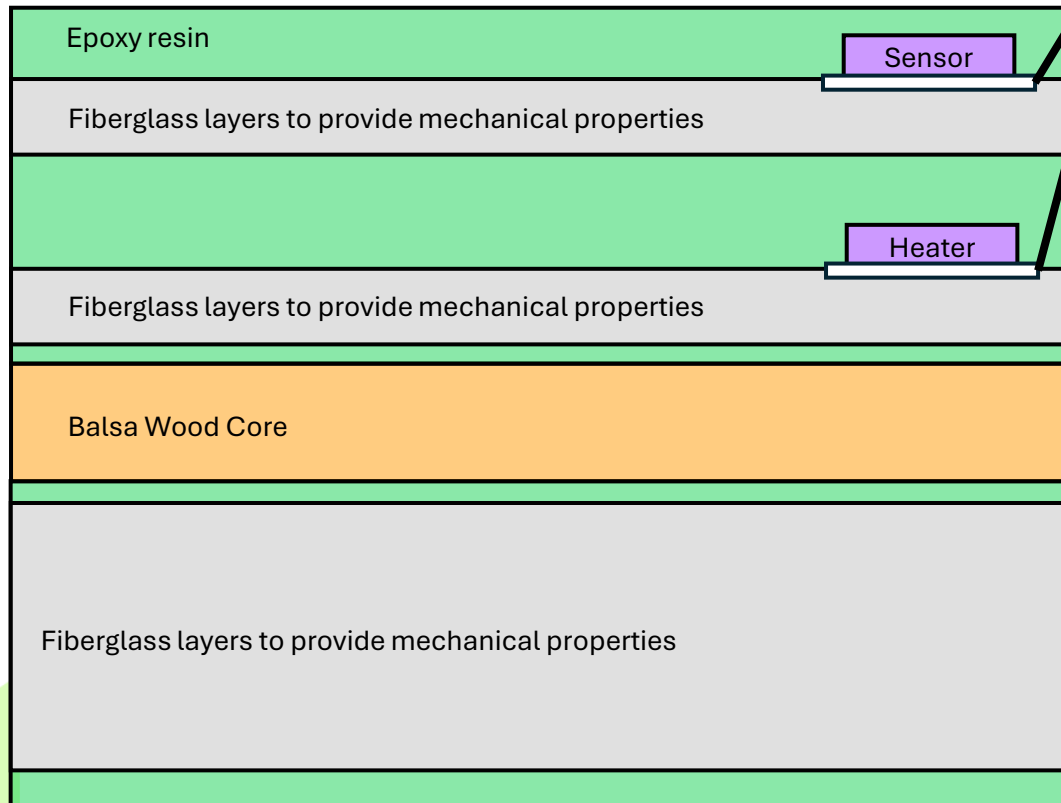
The sensor and heater are printed on a fiberglass fabric (thinner layer)

WIND BLADE STACK (Near Leading Edge and the tip)

3. EOLIAN PROJECT APPROACH vs EOLOGIX

DEMONSTRATORS DESIGN (Cross section)

Wind Blade surface



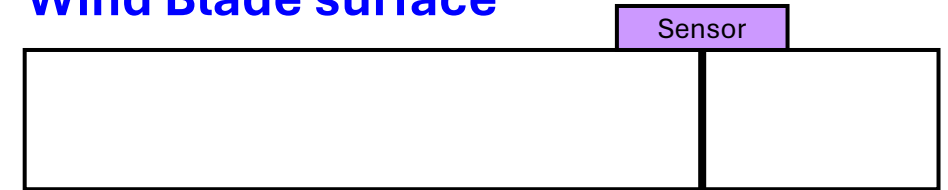
The sensor and heater are printed on a fiberglass fabric (thinner layer)

Wind Blade interior



Impedance sensor

Wind Blade surface



Wind Blade interior

Self-adhesive on the blade surface

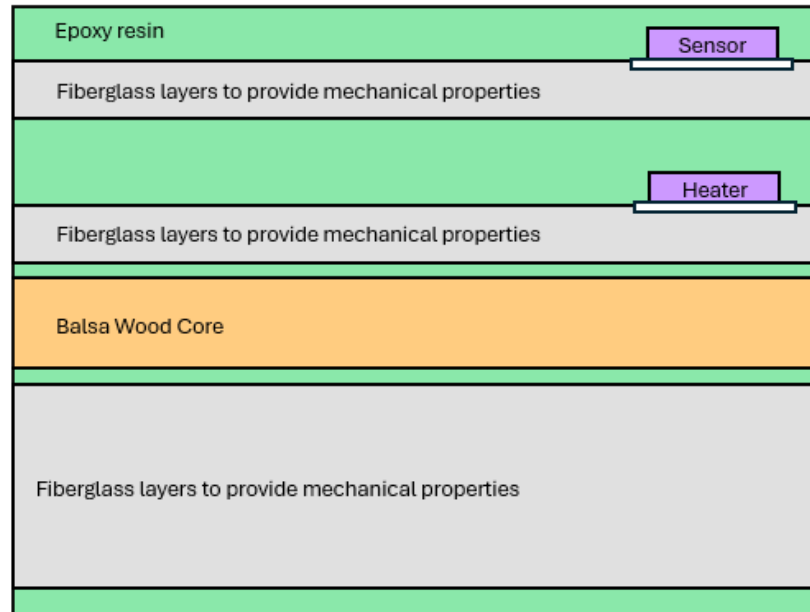


EOLOGIX-PING
ON-BLADE

3. Manufactured Demonstrators → Sensor and heater approach

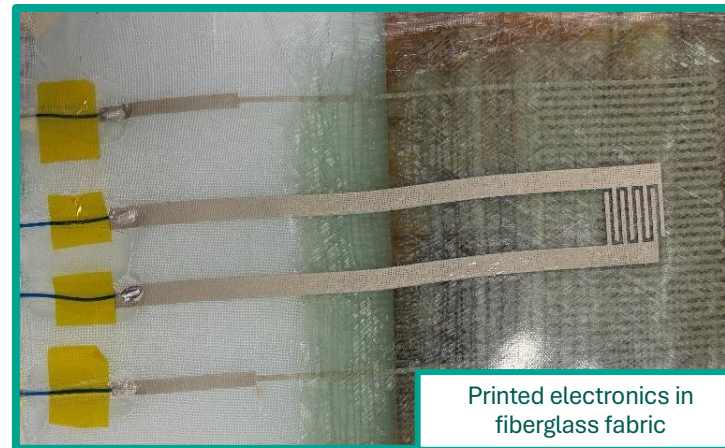
Composite → Vacuum Infusion Process

Wind Blade surface

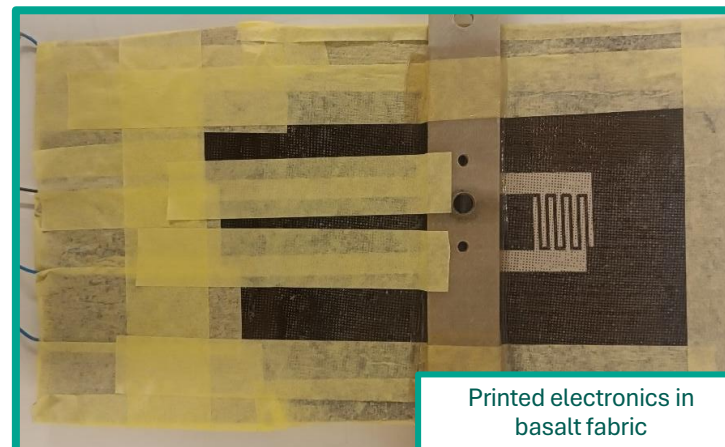


Wind Blade interior

Blade_wood_demo_ID

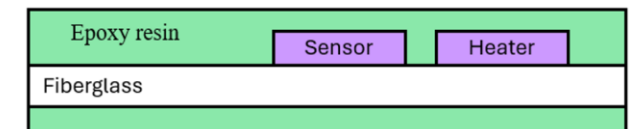


Blade_wood_demo_basalt_ID



Idea3_demo

NOT EOLIAN STACK



4. Ice detection approach → EIS measurements

Test conditions:

- Temperature = -10°C
- Humidity = 80 %RH

WIND TUNNEL ICE ACCRETION (water droplet speed 25 m/s)

WITHOUT ICE



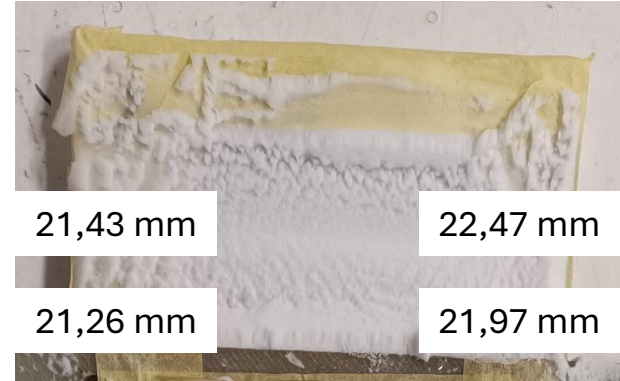
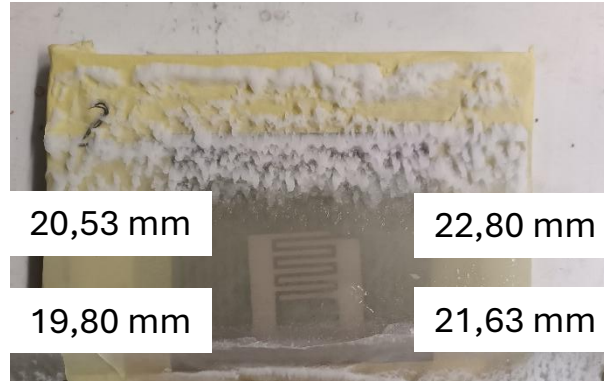
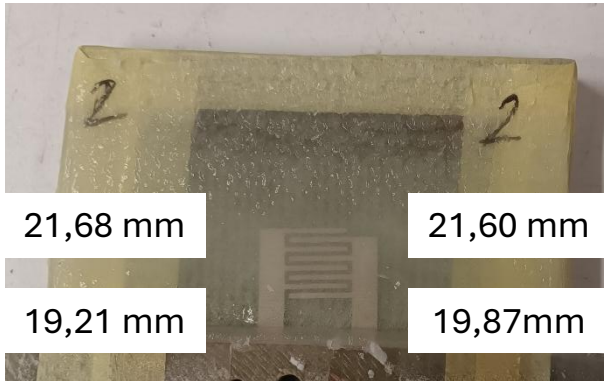
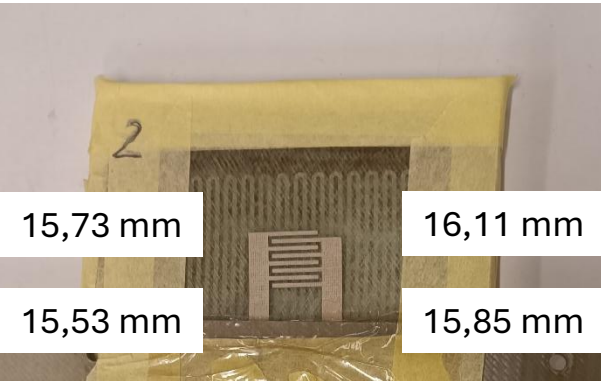
GLAZE ICE ≈ 5 mm



MIXED ICE ≈ 5 mm



RIME ICE ≈ 5 mm

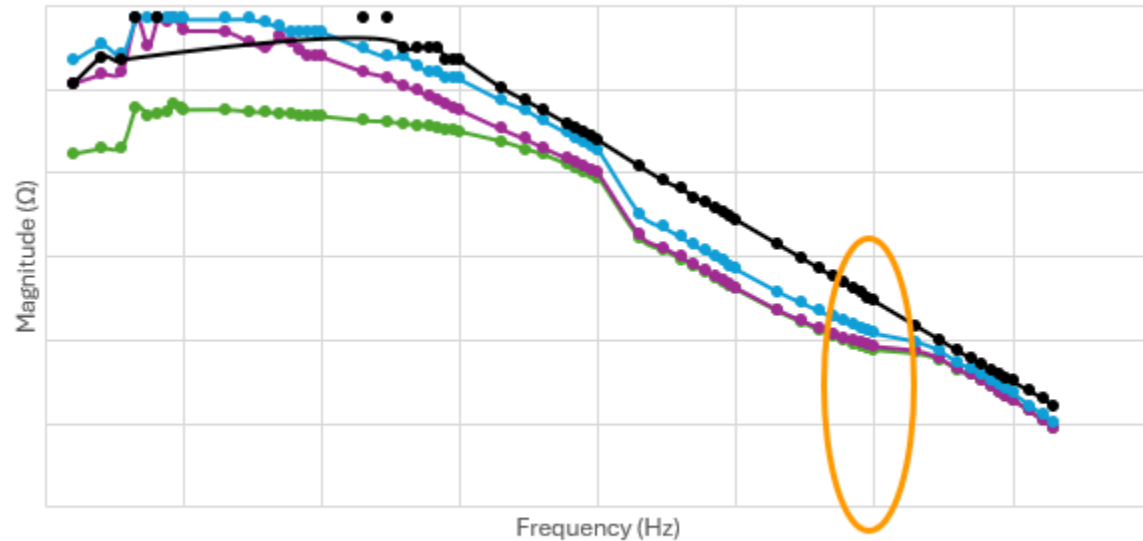


Sensing different types of ice with interdigitated transducers

4. Ice detection approach: Impedance measurements

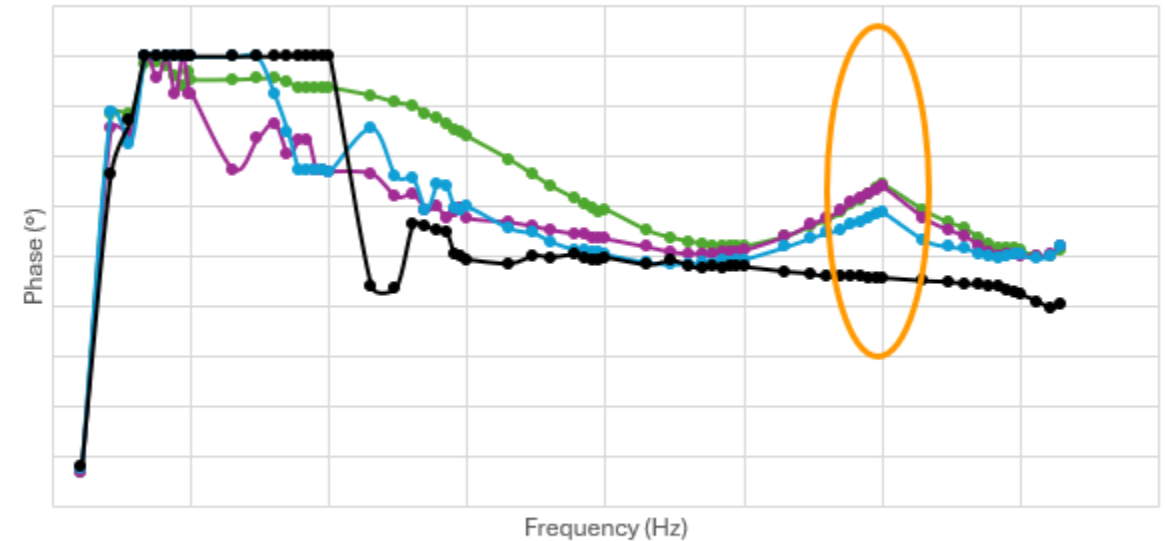
PRELIMINAR SELECTION OF THE FREQUENCY RANGE: Air measurement

Bode Magnitude diagram



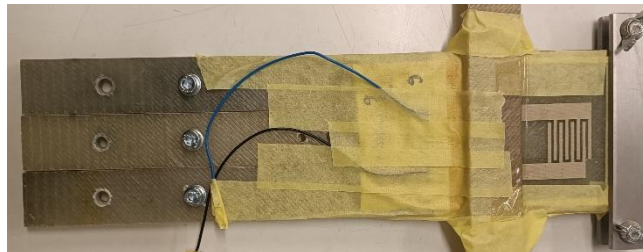
— FV110_BIAX_6_Mixed_16h — FV110_BIAX_6_Glaze_16h
— FV110_BIAX_6_Rime_16h — FV110_BIAX_6_Air

Bode Phase diagram

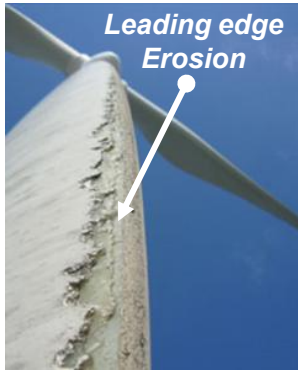


— FV110_BIAX_6_Mixed_16h — FV110_BIAX_6_Glaze_16h
— FV110_BIAX_6_Rime_16h — FV110_BIAX_6_Air

Frequency, Magnitude (Ω) and Phase ($^\circ$) range values deleted for being private information



Conclusions



Extended operational time

Cost savings → Integration of electronic circuits



Development of intelligent systems



Remote monitoring and control

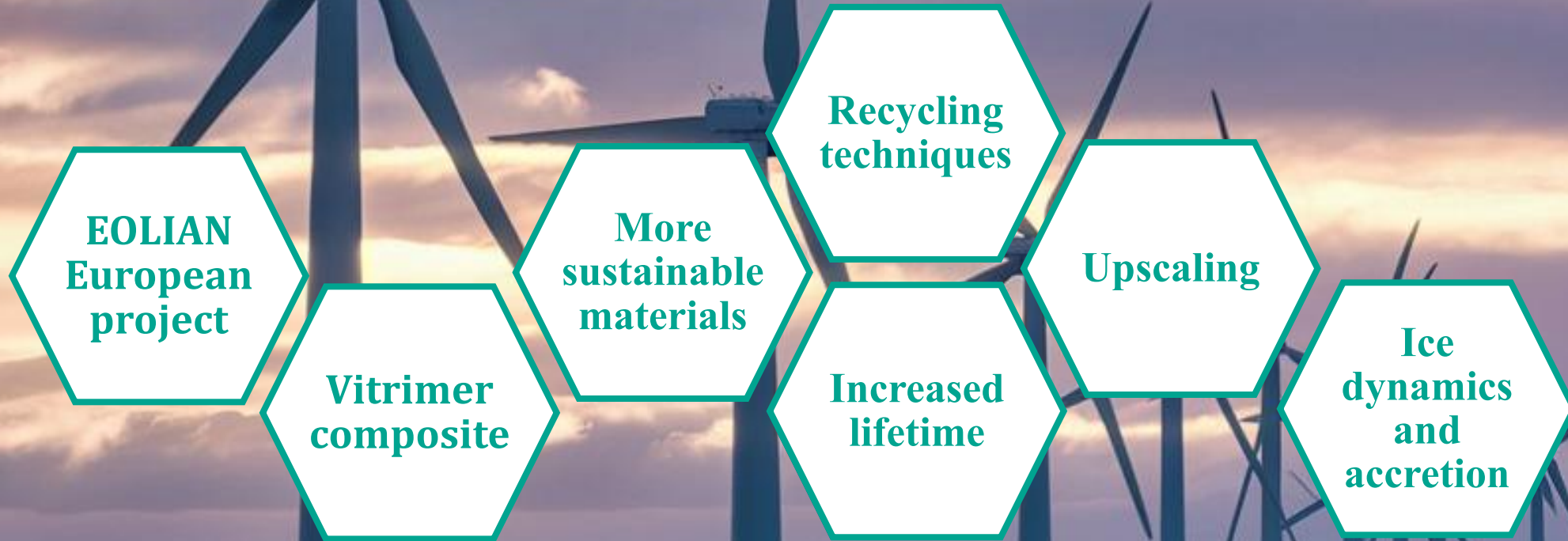


In situ detection



Multidisciplinary approach

Future work: Next steps



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Thank you for your attention!

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